



# *Hamiltonian formulation of reduced Vlasov-Maxwell equations*



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- importance of stability vs instability in devices involving a large number of charged particles interacting with fields: plasma physics (tokamaks), free electron lasers
- Here: reduced models of such systems (easier simulation, better understanding of the dynamics)

## *Outline*

- Hamiltonian description of charges particles and electromagnetic fields
- Reduction of Vlasov-Maxwell equations using Lie transforms



Alain J. BRIZARD (Saint Michael's College, Vermont, USA)

- Reduced Hamiltonian model for the Free Electron Laser



Romain BACHELARD (Synchrotron Soleil, Paris)  
Michel VITTOT (CPT, Marseille)

# Motion of a charged particle in electromagnetic fields

> in canonical form

$$H(\mathbf{p}, \mathbf{q}, t) = \frac{\left( \mathbf{p} - \frac{e}{c} \mathbf{A}(\mathbf{q}, t) \right)^2}{2m} + eV(\mathbf{q}, t) \quad \text{with } \{f, g\} = \frac{\partial f}{\partial \mathbf{q}} \cdot \frac{\partial g}{\partial \mathbf{p}} - \frac{\partial f}{\partial \mathbf{p}} \cdot \frac{\partial g}{\partial \mathbf{q}}$$

equations of motion :

$$\begin{cases} \dot{\mathbf{p}} = \{\mathbf{p}, H\} = -\frac{\partial H}{\partial \mathbf{q}} \\ \dot{\mathbf{q}} = \{\mathbf{q}, H\} = \frac{\partial H}{\partial \mathbf{p}} \end{cases}$$

> in non-canonical form: *physical variables*

$$\mathbf{v} = \frac{1}{m} \left( \mathbf{p} - \frac{e}{c} \mathbf{A}(\mathbf{q}, t) \right)$$

$$\mathbf{x} = \mathbf{q}$$

$$H(\mathbf{v}, \mathbf{x}, t) = \frac{1}{2} m \mathbf{v}^2 + eV(\mathbf{x}, t) \quad \text{with } \{f, g\} = \frac{1}{m} \left( \frac{\partial f}{\partial \mathbf{x}} \cdot \frac{\partial g}{\partial \mathbf{v}} - \frac{\partial f}{\partial \mathbf{v}} \cdot \frac{\partial g}{\partial \mathbf{x}} \right) + \frac{e \mathbf{B}}{m^2 c} \cdot \left( \frac{\partial f}{\partial \mathbf{v}} \times \frac{\partial g}{\partial \mathbf{v}} \right)$$

gyroscopic bracket

equations of motion :

$$\begin{cases} \dot{\mathbf{x}} = \{\mathbf{x}, H\} = \mathbf{v} \\ \dot{\mathbf{v}} = \{\mathbf{v}, H\} = \frac{e}{m} \left( \mathbf{E} + \frac{\mathbf{v} \times \mathbf{B}}{c} \right) \end{cases}$$

## *Definition: Hamiltonian system*

- a scalar function  $H$ , the Hamiltonian
- a Poisson bracket  $\{F, G\}$  with the properties
  - antisymmetric  $\{F, G\} = -\{G, F\}$
  - Leibnitz law  $\{F, GK\} = \{F, G\}K + G\{F, K\}$
  - Jacobi identity  $\{\{F, G\}, K\} + \{\{K, F\}, G\} + \{\{G, K\}, F\} = 0$

- equations of motion

$$\frac{dF}{dt} = \{F, H\}$$

- a conserved quantity

$$\{F, H\} = 0$$



## **Eulerian version: case of a density of charged particles**

- density of particles in phase space  $f(\mathbf{x}, \mathbf{v}, t)$

example:  $f(\mathbf{x}, \mathbf{v}, t) = \frac{1}{N} \sum_i \delta(\mathbf{x} - \mathbf{x}_i(t)) \delta(\mathbf{v} - \mathbf{v}_i(t))$  Klimontovitch distribution

- evolution given by the Vlasov equation

$$\frac{\partial f}{\partial t} = -\mathbf{v} \cdot \nabla f - \frac{e}{m} \left( \mathbf{E} + \frac{\mathbf{v}}{c} \times \mathbf{B} \right) \cdot \frac{\partial f}{\partial \mathbf{v}}$$

- Eulerian, not Lagrangian:

for any observable  $\mathcal{F}[f]$ , we have  $\frac{d\mathcal{F}}{dt} = \frac{\partial \mathcal{F}}{\partial t} = [\mathcal{F}, \mathcal{H}]$

- still a Hamiltonian system

Hamiltonian :  $\mathcal{H}[f] = \iint d^3x d^3v f \left( \frac{m}{2} \mathbf{v}^2 + eV \right)$

with  $[\mathcal{F}, \mathcal{G}] = \iint d^3x d^3v f \left\{ \frac{\delta \mathcal{F}}{\delta f}, \frac{\delta \mathcal{G}}{\delta f} \right\}$

## *Eulerian version: case of a density of charged particles*

- an example:  $\rho[f](\mathbf{x}_0) = e \int d^3v f(\mathbf{x}_0, \mathbf{v})$

$$\frac{\partial \rho}{\partial t} = [\rho, \mathcal{H}] = \int d^3x d^3v f \left\{ \frac{\delta \rho}{\delta f}, \frac{\delta \mathcal{H}}{\delta f} \right\}$$

- functional derivatives

$$\mathcal{F}[f + \phi] = \mathcal{F}[f] + \int d^3x d^3v \frac{\delta \mathcal{F}}{\delta f} \phi + O(\phi^2)$$

- here:  $\frac{\delta \rho}{\delta f} = e \delta(\mathbf{x} - \mathbf{x}_0)$  and  $\frac{\delta \mathcal{H}}{\delta f} = \frac{1}{2} m \mathbf{v}^2 + eV$

- therefore:  $\frac{\partial \rho}{\partial t} = -\frac{\partial}{\partial \mathbf{x}} \cdot \mathbf{J}$  with  $\mathbf{J}[f] = e \int d^3v f \mathbf{v}$

## *Vlasov-Maxwell equations: self-consistent dynamics*

> description of the dynamics of a collisionless plasma (low density)

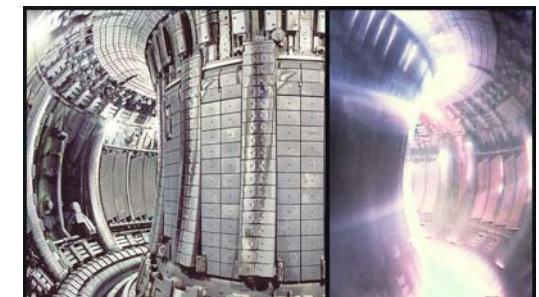
**Variables:** particle density  $f(\mathbf{x}, \mathbf{v}, t)$ , electric field  $\mathbf{E}(\mathbf{x}, t)$ , magnetic field  $\mathbf{B}(\mathbf{x}, t)$

$$\frac{\partial f}{\partial t} = -\mathbf{v} \cdot \nabla f - \frac{e}{m} \left( \mathbf{E} + \frac{\mathbf{v}}{c} \times \mathbf{B} \right) \cdot \frac{\partial f}{\partial \mathbf{v}}$$

$$\frac{\partial \mathbf{B}}{\partial t} = -c \nabla \times \mathbf{E}$$

$$\frac{\partial \mathbf{E}}{\partial t} = c \nabla \times \mathbf{B} - 4\pi \mathbf{J}$$

where  $\nabla \cdot \mathbf{E} = 4\pi\rho$  and  $\nabla \cdot \mathbf{B} = 0$



## Vlasov-Maxwell equations... still a Hamiltonian system

$$\text{Hamiltonian : } \mathcal{H}[\mathbf{E}, \mathbf{B}, f] = \iint d^3x d^3v f \frac{m}{2} \mathbf{v}^2 + \int d^3x \frac{|\mathbf{E}|^2 + |\mathbf{B}|^2}{8\pi}$$

$$\begin{aligned} \text{with } [\mathcal{F}, \mathcal{G}] &= \iint d^3x d^3v f \left\{ \frac{\delta \mathcal{F}}{\delta f}, \frac{\delta \mathcal{G}}{\delta f} \right\} \\ &\quad + \frac{4\pi e}{m} \iint d^3x d^3v \frac{\partial f}{\partial \mathbf{v}} \cdot \left[ \frac{\delta \mathcal{F}}{\delta \mathbf{E}} \frac{\delta \mathcal{G}}{\delta f} - \frac{\delta \mathcal{F}}{\delta f} \frac{\delta \mathcal{G}}{\delta \mathbf{E}} \right] \\ &\quad + 4\pi c \int d^3x \left[ \frac{\delta \mathcal{F}}{\delta \mathbf{E}} \cdot \nabla \times \frac{\delta \mathcal{G}}{\delta \mathbf{B}} - \nabla \times \frac{\delta \mathcal{F}}{\delta \mathbf{B}} \cdot \frac{\delta \mathcal{G}}{\delta \mathbf{E}} \right] \end{aligned}$$

Equation of motion for  $\mathcal{F}[\mathbf{E}, \mathbf{B}, f]$ : 
$$\boxed{\frac{d\mathcal{F}}{dt} = \frac{\partial \mathcal{F}}{\partial t} = [\mathcal{F}, \mathcal{H}]}$$

Remark:  $\text{div } \mathbf{B}$  et  $\text{div } \mathbf{E} - \int d^3p f$  are conserved quantities  
antisymmetry, Leibnitz, Jacobi

Morrison, PLA (1980)  
Marsden, Weinstein, Physica D (1982)

## *From microscopic to macroscopic Vlasov-Maxwell equations*

- Elimination (or decoupling) of fast time and small spatial scales for a better understanding of complex plasma phenomena

- reduced Maxwell equations in terms of  $\mathbf{D}$  and  $\mathbf{H}$

$$\nabla \cdot \mathbf{D} = 4\pi\rho_R$$

$$\frac{\partial \mathbf{D}}{\partial t} = c\nabla \times \mathbf{H} - 4\pi\mathbf{J}_R$$

$$\mathbf{D} = \mathbf{E} + 4\pi\mathbf{P}, \quad \mathbf{H} = \mathbf{B} - 4\pi\mathbf{M}$$

where

$$\rho_R = \rho + \nabla \cdot \mathbf{P}, \quad \mathbf{J}_R = \mathbf{J} - c\nabla \times \mathbf{M} - \frac{\partial \mathbf{P}}{\partial t}$$

↑                      ↑                      ↓  
reduced polarization density / magnetization current / polarization current density

- Can we represent the reduced Vlasov-Maxwell equations as a Hamiltonian system?  
Hint: use of Lie transforms
- *Deliverables:* Expressions of the polarization  $\mathbf{P}$  and magnetization  $\mathbf{M}$  vectors

## *Reduced fields as Lie transforms of $f$ , $\mathbf{E}$ and $\mathbf{B}$*

Given a functional  $\mathcal{S}[\mathbf{E}(\mathbf{x}, t), \mathbf{B}(\mathbf{x}, t), f(\mathbf{x}, \mathbf{v}, t)]$ , we define some new fields as

$$\boxed{\begin{pmatrix} \mathbf{D} \\ \mathbf{H} \\ F \end{pmatrix} = e^{-\mathcal{L}_s} \begin{pmatrix} \mathbf{E} \\ \mathbf{B} \\ f \end{pmatrix} = \begin{pmatrix} \mathbf{E} - [\mathcal{S}, \mathbf{E}] + \frac{1}{2}[\mathcal{S}, [\mathcal{S}, \mathbf{E}]] + \dots \\ \mathbf{B} - [\mathcal{S}, \mathbf{B}] + \frac{1}{2}[\mathcal{S}, [\mathcal{S}, \mathbf{B}]] + \dots \\ f - [\mathcal{S}, f] + \frac{1}{2}[\mathcal{S}, [\mathcal{S}, f]] + \dots \end{pmatrix}}$$

Remark: If the variable  $\chi$  is only a function of  $\mathbf{x}$

then  $e^{-\mathcal{L}_s}\chi$  is only a function of  $\mathbf{x}$

The functionals transforms into  $\bar{\mathcal{F}} = e^{-\mathcal{L}_s}\mathcal{F}$ ,

resulting in a new Hamiltonian and a new Poisson bracket...

## *Polarization, magnetization, reduced density, etc...*

$$\mathbf{P} = \frac{1}{4\pi} \left( e^{-\mathcal{L}_s} - 1 \right) \mathbf{E} = c \nabla \times \frac{\delta \mathcal{S}}{\delta \mathbf{B}} - \frac{e}{m} \int d^3v f \frac{\partial}{\partial \mathbf{v}} \left( \frac{\delta \mathcal{S}}{\delta f} \right) + \dots$$

$$\mathbf{M} = \frac{1}{4\pi} \left( 1 - e^{-\mathcal{L}_s} \right) \mathbf{B} = c \nabla \times \frac{\delta \mathcal{S}}{\delta \mathbf{E}} + \dots$$

so that 
$$\begin{cases} \mathbf{D} = \mathbf{E} + 4\pi \mathbf{P} \\ \mathbf{H} = \mathbf{B} - 4\pi \mathbf{M} \end{cases}$$

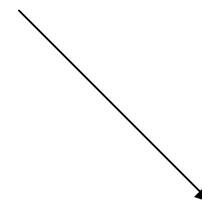
Reduced evolution operator 
$$\frac{\partial \bar{\mathcal{F}}}{\partial \bar{t}} \equiv \left( e^{-\mathcal{L}_s} \frac{\partial}{\partial t} e^{\mathcal{L}_s} \right) \bar{\mathcal{F}}$$

$$= e^{-\mathcal{L}_s} \left[ e^{\mathcal{L}_s} \bar{\mathcal{F}}, e^{\mathcal{L}_s} \bar{\mathcal{H}} \right] = [\bar{\mathcal{F}}, \bar{\mathcal{H}}]$$

## Reduced Vlasov-Maxwell equations

$$\frac{\partial \mathbf{D}}{\partial \bar{t}} = c \nabla \times \mathbf{H} - 4\pi \bar{\mathbf{J}}$$

$$\frac{\partial \mathbf{H}}{\partial \bar{t}} = -c \nabla \times \mathbf{D}$$



$$\frac{\partial \mathbf{D}}{\partial t} = \frac{\partial \mathbf{D}}{\partial \bar{t}} + [\mathbf{D}, \mathcal{H} - \bar{\mathcal{H}}] = c \nabla \times \mathbf{H} - 4\pi \mathbf{J}_R$$

$$\frac{\partial \mathbf{H}}{\partial t} = \frac{\partial \mathbf{H}}{\partial \bar{t}} + [\mathbf{H}, \mathcal{H} - \bar{\mathcal{H}}] = -c \nabla \times \mathbf{D} - 4\pi \frac{\partial \mathbf{M}}{\partial t} + 4\pi c \nabla \times \mathbf{P}$$

Reduced Vlasov equation  $\frac{\partial F}{\partial \bar{t}} = -\mathbf{v} \cdot \nabla F - \frac{e}{m} \left( \mathbf{D} + \frac{\mathbf{v}}{c} \times \mathbf{H} \right) \cdot \frac{\partial F}{\partial \mathbf{v}}$

$$F = f - \left\{ f, \frac{\delta \mathcal{S}}{\delta f} \right\} - \frac{4\pi e}{m} \frac{\partial f}{\partial \mathbf{v}} \cdot \frac{\delta \mathcal{S}}{\delta \mathbf{E}} + \dots$$



guiding center theory / gyrokinetics

## What $\mathcal{S}$ ?

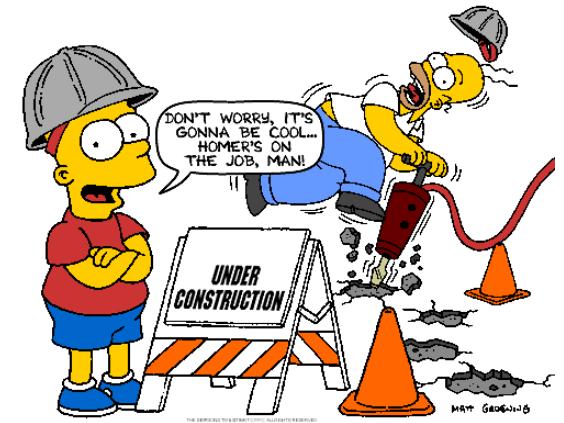
$$\begin{pmatrix} \mathbf{D} \\ \mathbf{H} \\ F \end{pmatrix} = e^{-\mathcal{L}_s t} \begin{pmatrix} \mathbf{E} \\ \mathbf{B} \\ f \end{pmatrix}$$

- Elimination of small spatial and fast time (averaging) scales of  $f(\mathbf{x}, \mathbf{v}, t)$  :  
guiding-center      } collisionless plasmas (low frequency phenomena)  
gyrokinetics  
reduced models for free electron lasers
- Use of KAM algorithms (at least one step process)

For  $\mathbf{F} = f + \delta f$ , homological equation  $\mathbb{P}(\delta f + [\mathcal{S}, f]) = 0$

- Advantages: preserve the structure of the equations,  
invertible, symbolic calculus

Brizard, Hahm, Rev. Mod. Phys. (2007)



## *Strategies to reduce Vlasov-Maxwell equations*

- > rigorous:  $\bar{\mathcal{H}} = e^{-\mathcal{L}_s t} \mathcal{H}$
- > non-rigorous: truncate the Hamiltonian system
  - the equations of motion
  - the Hamiltonian and the Poisson bracket
- > the canonical version provides a way out...



## *Reduced model for the Free Electron Laser*

**From:** Vlasov-Maxwell Hamiltonian

$$\mathcal{H}[\mathbf{E}, \mathbf{B}, f] = \iint d^3x d^3p f(\mathbf{x}, \mathbf{p}) \sqrt{1 + \mathbf{p}^2} + \int d^3x \frac{|\mathbf{E}|^2 + |\mathbf{B}|^2}{2}$$

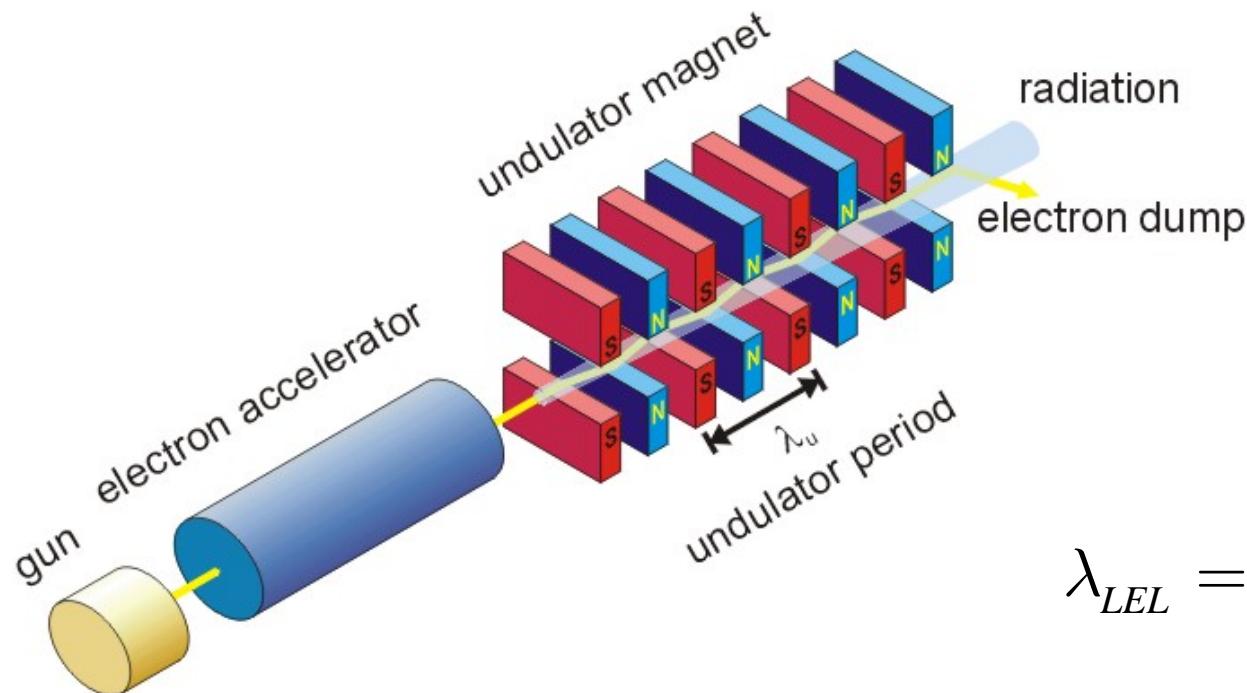
**To:** Bonifacio's reduced FEL Hamiltonian model

$$H[f, I, \varphi] = \iint d\theta dp f(\theta, p) \left( \frac{p^2}{2} + 2\sqrt{I} \sin(\theta - \varphi) \right)$$

with  $(I, \varphi)$  intensity and phase of the electromagnetic wave

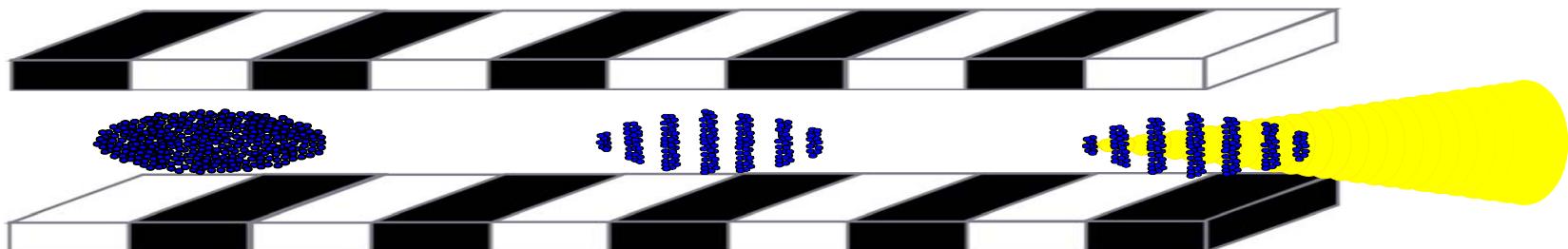
**... in a Hamiltonian way**

# *A Free Electron... what?*



General layout of free-electron laser

$$\lambda_{LEL} = \frac{\lambda_u}{2\gamma^2} (1 + K_{rms}^2)$$



## Vlasov-Maxwell: canonical version

① Change of variables:  $(f, \mathbf{E}, \mathbf{B}) \mapsto (f_m, \mathbf{Y}, \mathbf{A})$

$$f(\mathbf{x}, \mathbf{p}) = f_m(\mathbf{x}, \mathbf{p} + \mathbf{A}(\mathbf{x}))$$

$$\mathbf{E} = -\mathbf{Y}$$

$$\mathbf{B} = \nabla \times \mathbf{A}$$

Bracket: canonical

$$[\mathcal{F}, \mathcal{G}] = \iint d^3x d^3p f_m \left[ \nabla \frac{\delta \mathcal{F}}{\delta f_m} \cdot \frac{\partial}{\partial \mathbf{p}} \frac{\delta \mathcal{G}}{\delta f_m} - \frac{\partial}{\partial \mathbf{p}} \frac{\delta \mathcal{F}}{\delta f_m} \cdot \nabla \frac{\delta \mathcal{G}}{\delta f_m} \right] + \int d^3x \left[ \frac{\delta \mathcal{F}}{\delta \mathbf{A}} \cdot \frac{\delta \mathcal{G}}{\delta \mathbf{Y}} - \frac{\delta \mathcal{F}}{\delta \mathbf{Y}} \cdot \frac{\delta \mathcal{G}}{\delta \mathbf{A}} \right]$$

$$\text{Hamiltonian: } \mathcal{H} = \iint d^3x d^3p f_m \sqrt{1 + (\mathbf{p} - \mathbf{A})^2} + \int d^3x \frac{|\mathbf{Y}|^2 + |\nabla \times \mathbf{A}|^2}{2}$$

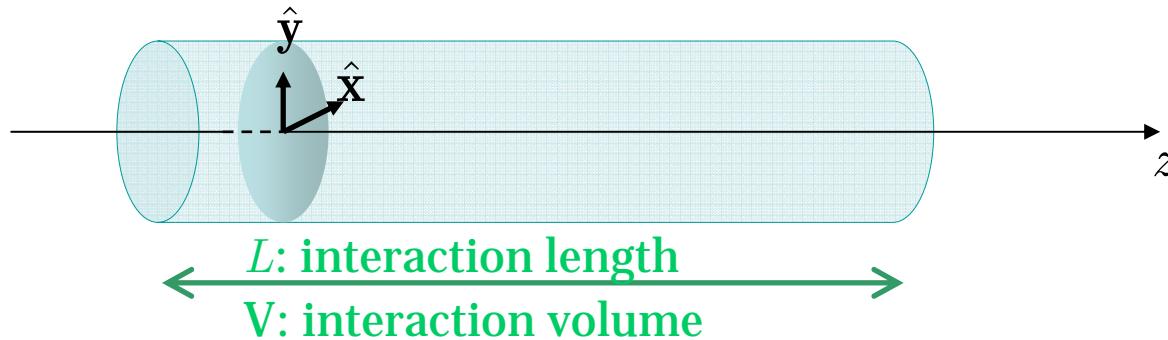
② Translation of  $\mathbf{A}$  by a constant function (external field-undulator):  $\mathbf{A}(\mathbf{x}, t) \mapsto \mathbf{A}_w(\mathbf{x}) + \mathbf{A}(\mathbf{x}, t)$

Bracket: canonical (canonical transformation)

$$\text{Hamiltonian: } \mathcal{H} = \iint d^3x d^3p f_m \sqrt{1 + (\mathbf{p} - \mathbf{A}_w - \mathbf{A})^2} + \int d^3x \frac{|\mathbf{Y}|^2 + 2\nabla \times \mathbf{A}_w \cdot \nabla \times \mathbf{A} + |\nabla \times \mathbf{A}|^2}{2}$$

$$\mathbf{A}_w \text{ helicoidal undulator: } \mathbf{A}_w = \frac{a_w}{\sqrt{2}} \left( e^{-ik_w z} \hat{\mathbf{e}} + e^{ik_w z} \hat{\mathbf{e}}^* \right)$$

## One mode for the radiated field



### ③ Paraxial approximation and circularly polarized radiated field

$$\mathbf{A} = -\frac{i}{\sqrt{2}}(a \mathbf{e}^{ikz} \hat{\mathbf{e}} - a^* \mathbf{e}^{-ikz} \hat{\mathbf{e}}^*) \quad \text{where } \hat{\mathbf{e}} = \frac{\hat{\mathbf{x}} + i\hat{\mathbf{y}}}{\sqrt{2}}$$

$$\mathbf{Y} = \frac{k}{\sqrt{2}}(a \mathbf{e}^{ikz} \hat{\mathbf{e}} + a^* \mathbf{e}^{-ikz} \hat{\mathbf{e}}^*)$$

Remark:  $a$  does not depend on  $x$  and  $y$  but depends on time (dynamical variable)

Bracket:  $[\mathcal{F}, \mathcal{G}] = \iint d^3x d^3p f_m \left[ \nabla \frac{\delta \mathcal{F}}{\delta f_m} \cdot \frac{\partial}{\partial \mathbf{p}} \frac{\delta \mathcal{G}}{\delta f_m} - \frac{\partial}{\partial \mathbf{p}} \frac{\delta \mathcal{F}}{\delta f_m} \cdot \nabla \frac{\delta \mathcal{G}}{\delta f_m} \right] + \frac{ik}{V} \left( \frac{\partial \mathcal{F}}{\partial a} \frac{\partial \mathcal{G}}{\partial a^*} - \frac{\partial \mathcal{F}}{\partial a^*} \frac{\partial \mathcal{G}}{\partial a} \right)$

Hamiltonian:  $\mathcal{H} = \iint d^3x d^3p f_m \sqrt{1 + \mathbf{p}^2 + aa^* - i\sqrt{2}(a \mathbf{e}^{ikz} \hat{\mathbf{e}} - a^* \mathbf{e}^{-ikz} \hat{\mathbf{e}}^*) \cdot \mathbf{A}_w + |\mathbf{A}_w|^2} + k^2 V a a^* - \frac{ikS}{\sqrt{2}} \int dz (a \mathbf{e}^{ikz} \hat{\mathbf{e}} - a^* \mathbf{e}^{-ikz} \hat{\mathbf{e}}^*) \cdot \nabla \times \mathbf{A}_w$

## Dimensional reduction

④ The fields do not depend on  $x$  and  $y \Rightarrow$  no transverse velocity dispersion

$$f(\mathbf{x}, \mathbf{p}) = \hat{f}(\mathbf{x}, p_{\parallel}) \delta(\mathbf{p}_{\perp}) \quad \text{if } \mathbf{p}_{\perp}(t=0) = 0$$

If  $\mathbf{p}_{\perp}(t) = 0$  then no modification of the  $(x, y)$  distribution

$$f(\mathbf{x}, \mathbf{p}) = \tilde{f}(z, p_{\parallel}) \delta(\mathbf{p}_{\perp}) \delta(x) \delta(y) \quad \text{if } x(t=0) = y(t=0) = 0 \quad (\text{injection at the center})$$

Bracket:  $[\mathcal{F}, \mathcal{G}] = \iint dz dp_{\parallel} \tilde{f} \left[ \frac{\partial}{\partial p_{\parallel}} \frac{\delta \mathcal{F}}{\delta \tilde{f}} \frac{\partial}{\partial z} \frac{\delta \mathcal{G}}{\delta \tilde{f}} - \frac{\partial}{\partial z} \frac{\delta \mathcal{F}}{\delta \tilde{f}} \frac{\partial}{\partial p_{\parallel}} \frac{\delta \mathcal{G}}{\delta \tilde{f}} \right] + \frac{ik}{V} \left( \frac{\partial \mathcal{F}}{\partial a} \frac{\partial \mathcal{G}}{\partial a^*} - \frac{\partial \mathcal{F}}{\partial a^*} \frac{\partial \mathcal{G}}{\partial a} \right)$

Hamiltonian:  $\mathcal{H} = \iint dz dp_{\parallel} \tilde{f} \sqrt{1 + p_{\parallel}^2 + aa^* - i\sqrt{2} (a e^{ikz} \hat{\mathbf{e}} - a^* e^{-ikz} \hat{\mathbf{e}}^*) \cdot \mathbf{A}_w + |\mathbf{A}_w|^2}$   
 $+ k^2 V a a^* - \frac{ikS}{\sqrt{2}} \int dz (a e^{ikz} \hat{\mathbf{e}} - a^* e^{-ikz} \hat{\mathbf{e}}^*) \cdot \nabla \times \mathbf{A}_w$

⑤ Autonomization:  $[\mathcal{F}, \mathcal{G}]_a = [\mathcal{F}, \mathcal{G}] + \frac{\partial \mathcal{F}}{\partial t} \frac{\partial \mathcal{G}}{\partial E} - \frac{\partial \mathcal{F}}{\partial E} \frac{\partial \mathcal{G}}{\partial t}$  with  $\mathcal{H}_a = \mathcal{H} + E$

Time dependent transformation (canonical):

$$\hat{f}(\theta, p_{\parallel}) = \tilde{f}(z, p_{\parallel}) \quad \text{with } \theta = (k + k_w)z - kt$$

$$\hat{a} = a e^{ikt}$$

vanishing

$$\hat{E} = E + V k^2 a a^* \text{ and } \hat{t} = t$$

Bracket: canonical

Hamiltonian:  $\mathcal{H} = \iint d\theta dp_{\parallel} \hat{f} \left( \sqrt{1 + p_{\parallel}^2 + \hat{a} \hat{a}^* - ia_w (\hat{a} e^{i\theta} - \hat{a}^* e^{-i\theta})} + a_w^2 - \frac{k}{k + k_w} p_{\parallel} \right)$

## Bonifacio's FEL model

⑥ Resonance condition:  $p_{\parallel} = p_R + p$  with  $|p| \ll p_R$

weak radiated field:  $|\hat{a}| \ll \gamma_R \equiv \sqrt{1 + p_R^2}$

Bracket:  $[\mathcal{F}, \mathcal{G}] = (k + k_w) \iint d\theta dp \hat{f} \left[ \frac{\partial}{\partial \theta} \frac{\delta \mathcal{F}}{\delta \hat{f}} \frac{\partial}{\partial p} \frac{\delta \mathcal{G}}{\delta \hat{f}} - \frac{\partial}{\partial p} \frac{\delta \mathcal{F}}{\delta \hat{f}} \frac{\partial}{\partial \theta} \frac{\delta \mathcal{G}}{\delta \hat{f}} \right] + \frac{i}{kV} \left( \frac{\partial \mathcal{F}}{\partial \hat{a}^*} \frac{\partial \mathcal{G}}{\partial \hat{a}} - \frac{\partial \mathcal{F}}{\partial \hat{a}} \frac{\partial \mathcal{G}}{\partial \hat{a}^*} \right)$

Hamiltonian:  $\mathcal{H} = \iint d\theta dp \hat{f}(\theta, p) \left( \frac{1 + a_w^2}{\gamma_R^3} \frac{p^2}{2} - \frac{ia_w}{\gamma_R} (\hat{a} e^{i\theta} - \hat{a}^* e^{-i\theta}) \right)$

⑦ Normalization

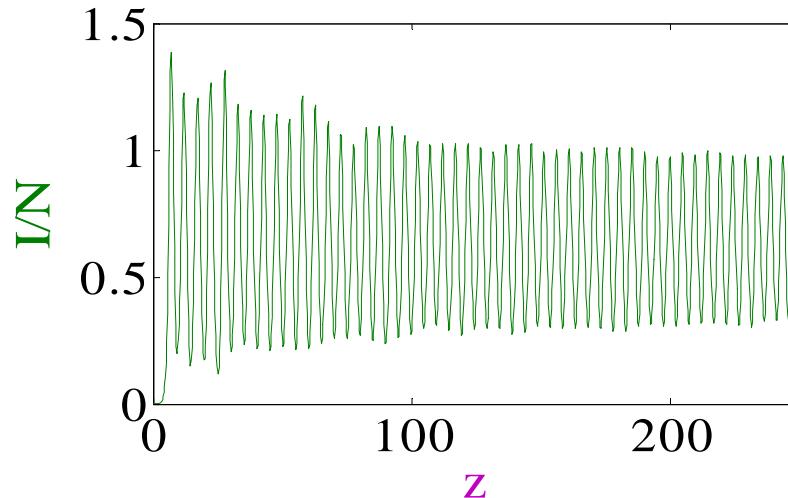
⑧ Transformation (canonical) into intensity/phase  $a = i\sqrt{I}e^{-i\varphi}$

Bracket: canonical  $[\mathcal{F}, \mathcal{G}] = \iint d\theta dp f \left[ \frac{\partial}{\partial \theta} \frac{\delta \mathcal{F}}{\delta f} \frac{\partial}{\partial p} \frac{\delta \mathcal{G}}{\delta f} - \frac{\partial}{\partial p} \frac{\delta \mathcal{F}}{\delta f} \frac{\partial}{\partial \theta} \frac{\delta \mathcal{G}}{\delta f} \right] + \frac{\partial \mathcal{F}}{\partial \varphi} \frac{\partial \mathcal{G}}{\partial I} - \frac{\partial \mathcal{F}}{\partial I} \frac{\partial \mathcal{G}}{\partial \varphi}$

Hamiltonian:  $\mathcal{H} = \iint d\theta dp f(\theta, p) \frac{p^2}{2} + 2\sqrt{I} \iint d\theta dp f(\theta, p) \cos(\theta - \varphi)$

## *Outlook: on the use of reduced Hamiltonian models*

$$H_N = \sum_{j=1}^N \frac{\mathbf{p}_j^2}{2} + 2\sqrt{\frac{I}{N}} \sum_{j=1}^N \cos(\theta_j - \varphi)$$



Long-range interacting systems : QSS, transition to equilibrium,...

Gyrokinetics: understand plasma disruption, control,...

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References: Bachelard, Chandre, Vittot, PRE (2008)

Chandre, Brizard, in preparation.